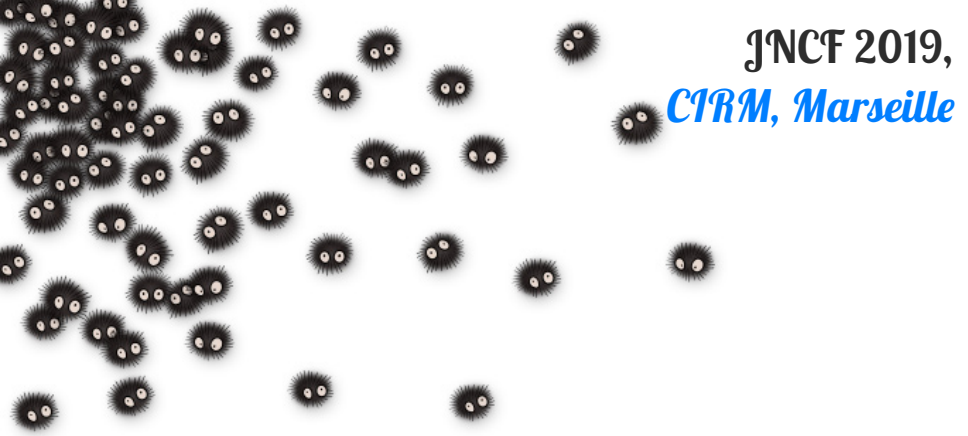




JNCF 2019,
CIRM, Marseille

A New Lower Bound on the Hilbert Number for Quartic Systems

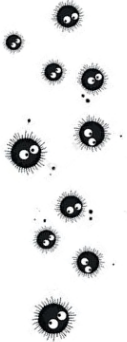
F. Bréhard^{1,2}, N. Brisebarre¹, M. Joldes² and W. Tucker^{1,3}

1. IUP, ENS de Lyon

2. IRTAS-CNRS, Toulouse

3. CIRA, Uppsala universitet

Outline

- 
- 1 A quartic example for Hilbert 16th problem
 - 2 Computing Abelian integrals with rigorous polynomial approximations
 - 3 Wronskian and extended Chebyshev systems
 - 4 Conclusion

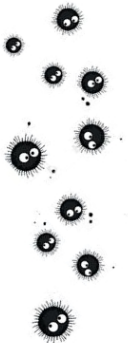
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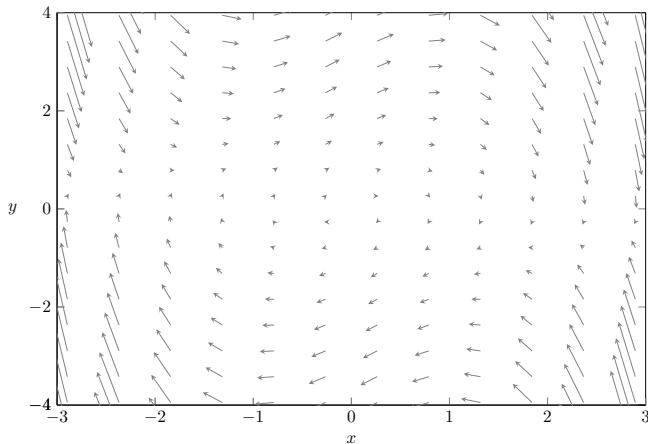


Hilbert's 16th problem (second part)

For a given integer n , what is the maximum number $\mathcal{H}(n)$ of **limit cycles** a **polynomial** vector field of degree **at most n** in the **plane** can have?

D. Hilbert, International Congress of Mathematicians, Paris, 1900

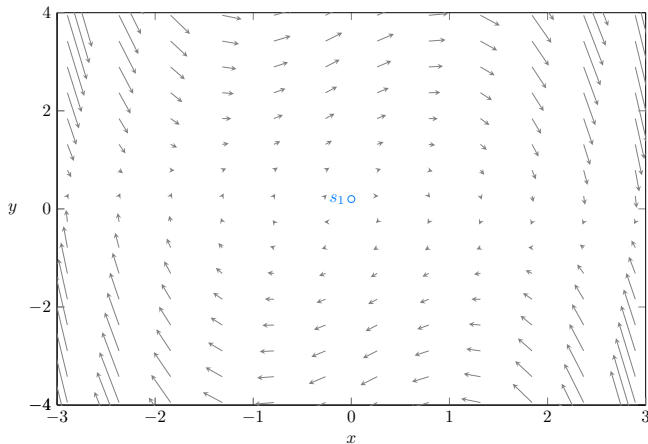
Hilbert's 16th Problem



Van der Pol oscillator:

$$\begin{cases} \dot{x} = y \\ \dot{y} = -x + (1 - x^2)y \end{cases}$$

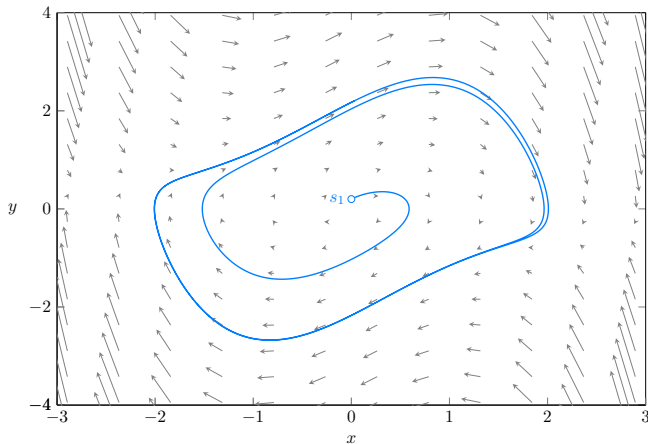
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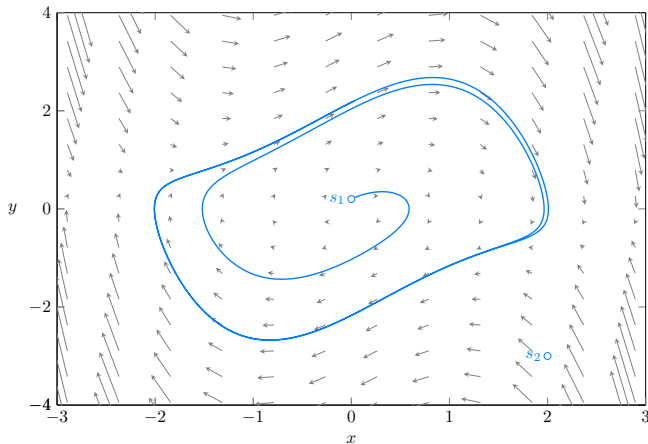
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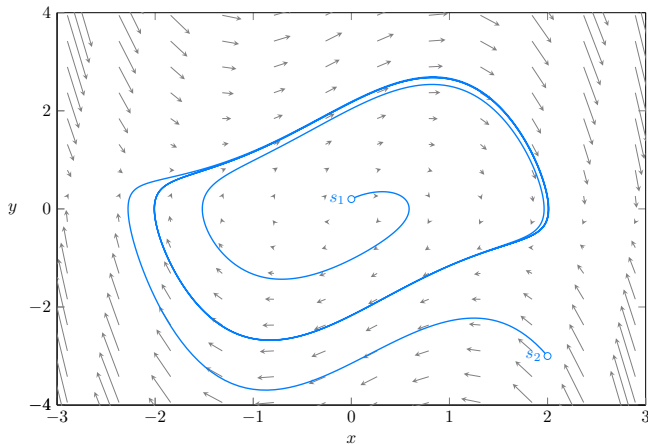
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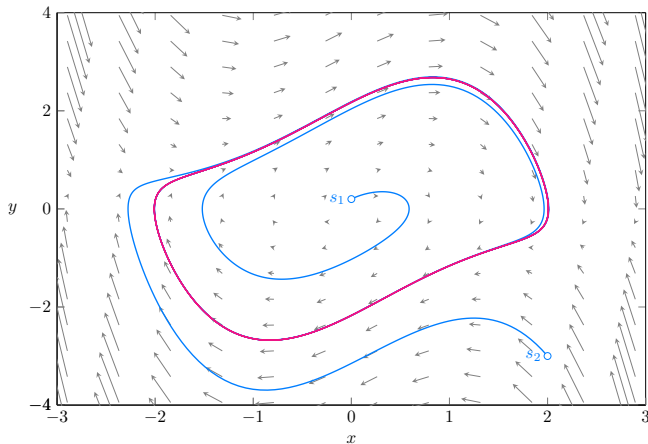
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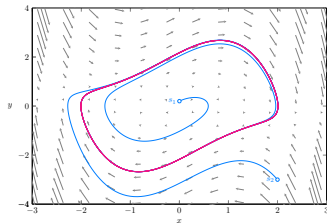


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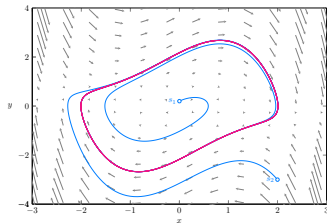


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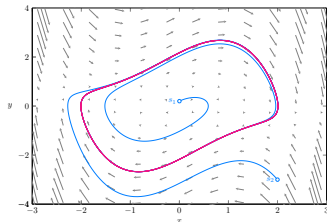


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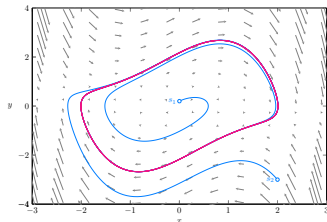


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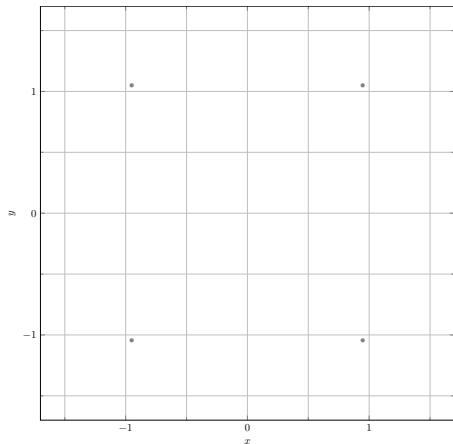
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- We prove $\mathcal{H}(4) \geq 24$.



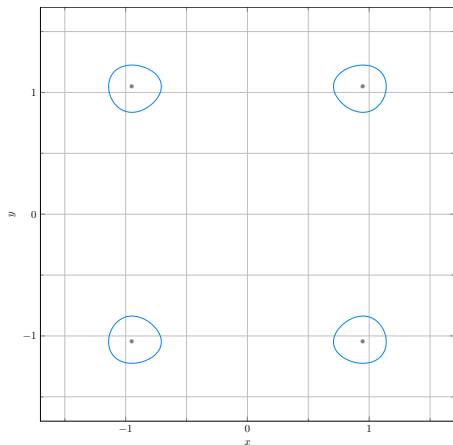
Infinitesimal Hilbert's 16th Problem



$$H(x, y) = (x^2 - 0.9)^2 + (y^2 - 1.1)^2$$

T. Johnson, A quartic system with twenty-six limit cycles,
Experimental Mathematics, 2011

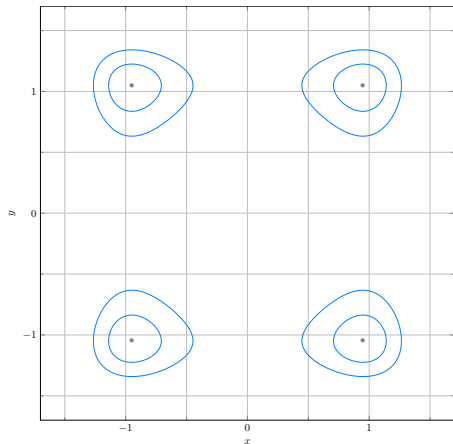
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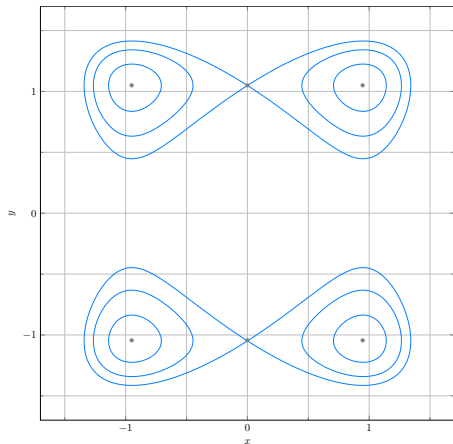
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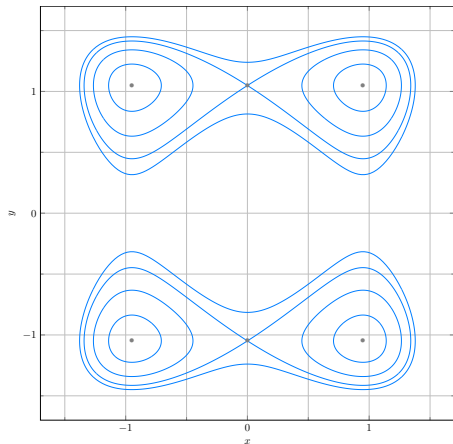
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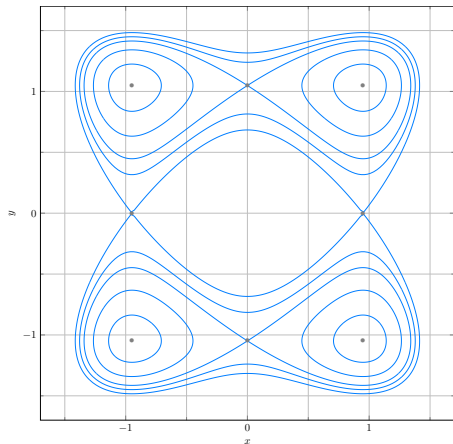
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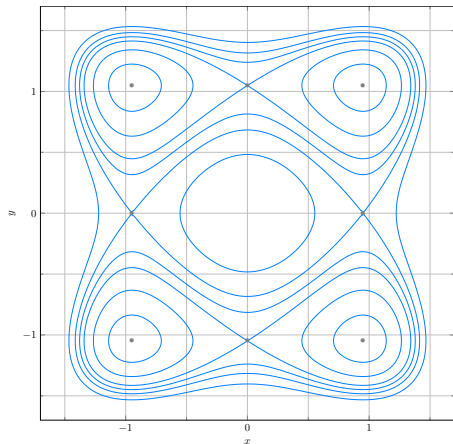
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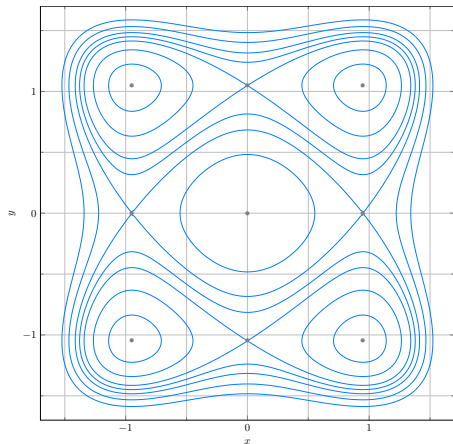
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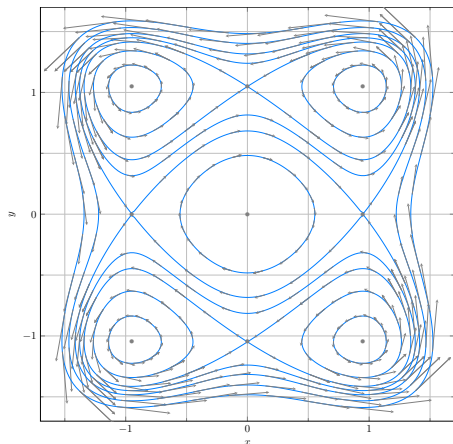
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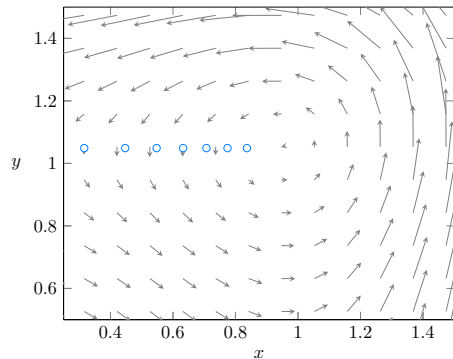


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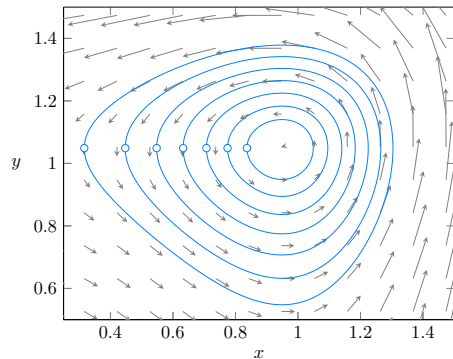


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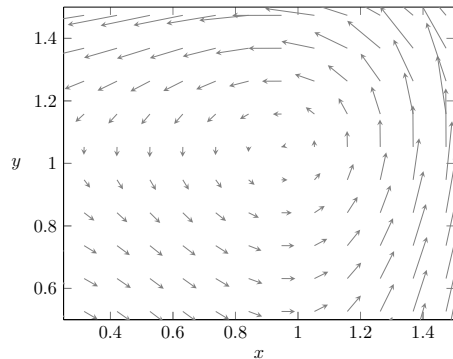


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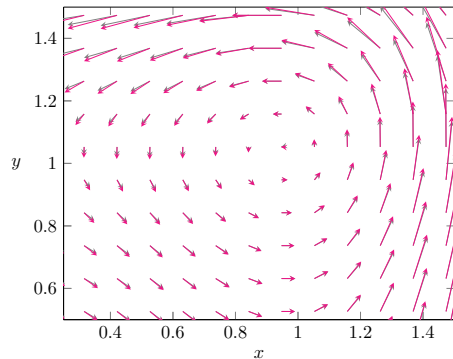


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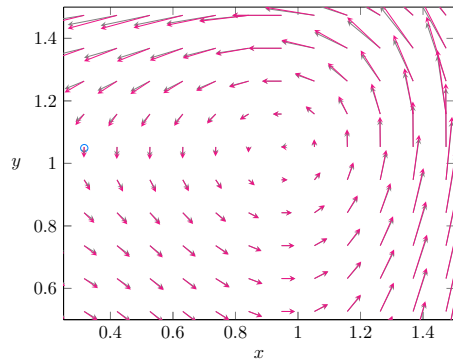


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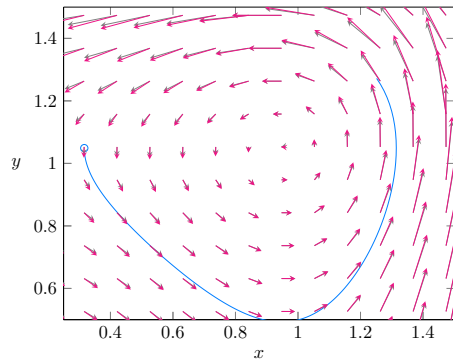


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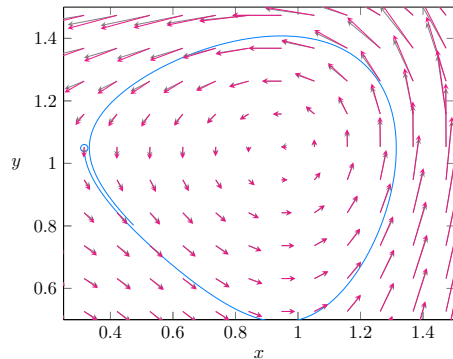


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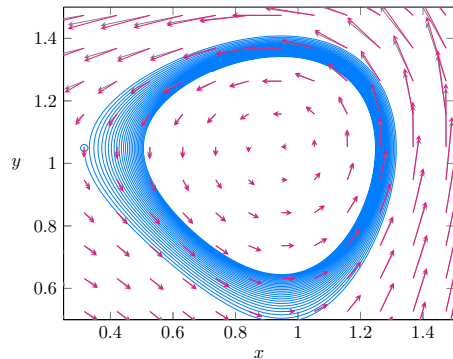


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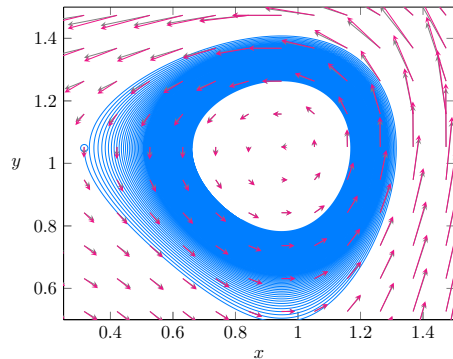


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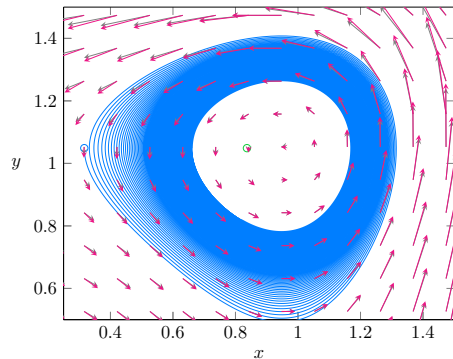


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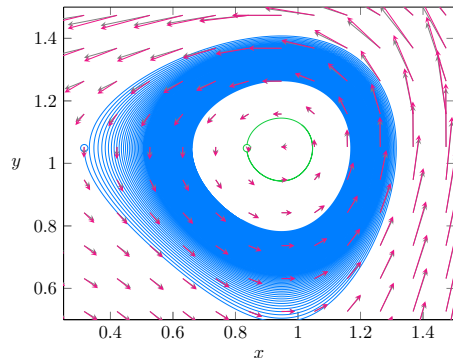


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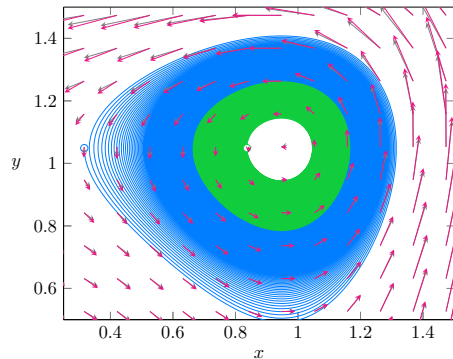


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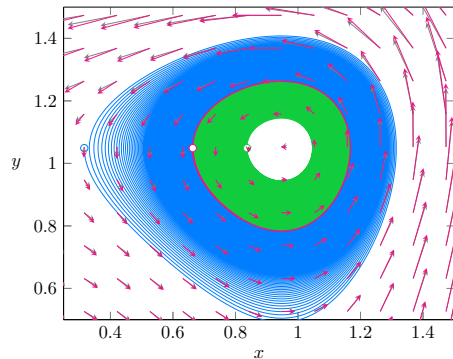


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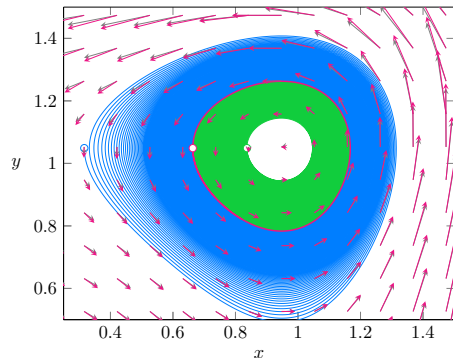
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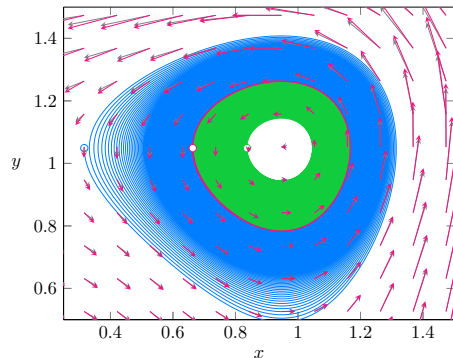
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For a given integer n , what is the maximal number $\mathcal{Z}(n)$ of limit cycles a **perturbed Hamiltonian** vector field of the form:

$$\begin{cases} \dot{x} = -\partial_y H(x, y) + \varepsilon f(x, y) \\ \dot{y} = \partial_x H(x, y) + \varepsilon g(x, y) \end{cases}$$

can have when $\varepsilon \rightarrow 0$, with:

- $H(x, y)$ a polynomial potential function of degree $n + 1$
- f, g polynomial perturbations of degree n



T. Johnson, A quartic system with twenty-six limit cycles, *Experimental Mathematics*, 2011

Infinitesimal Hilbert's 16th problem

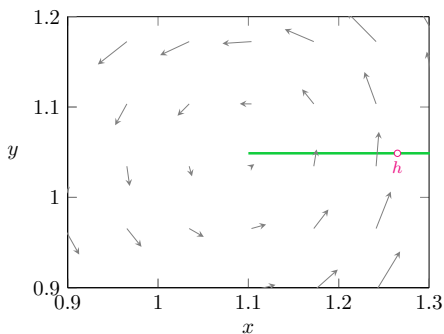
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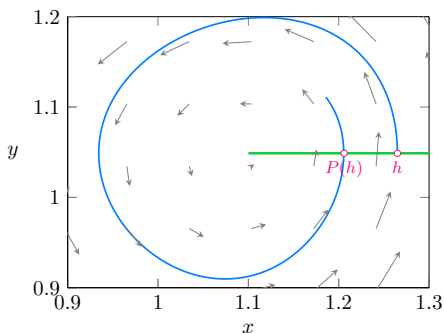
- $H(x, y)$ a polynomial potential function of degree $n + 1$
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- $\mathcal{Z}(n) < \infty$ for all n
- Pessimistic upper bounds

A Fundamental Tool: the Poincaré-Pontryagin Theorem



$$\begin{cases} \dot{x} = -\partial_y H(x, y) + \varepsilon f(x, y) \\ \dot{y} = \partial_x H(x, y) + \varepsilon g(x, y) \end{cases}$$

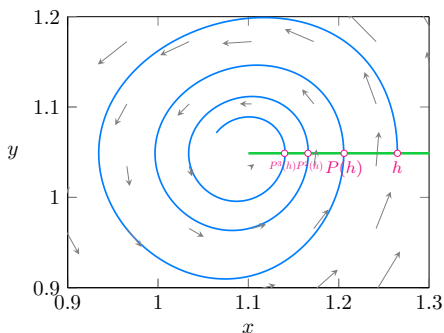
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■ Poincaré first return map $P(h)$

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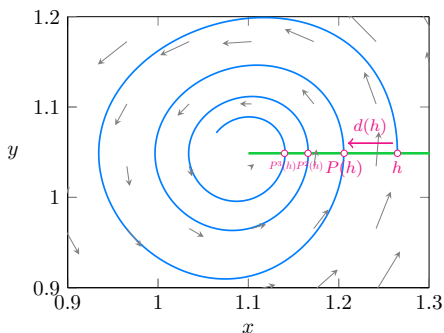
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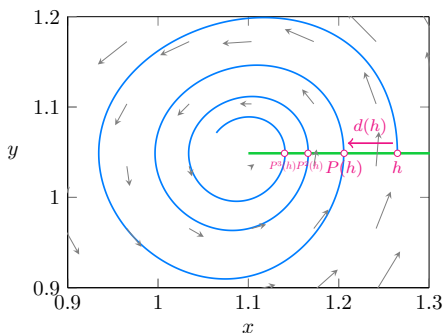
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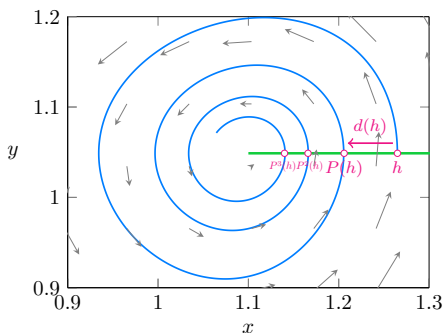
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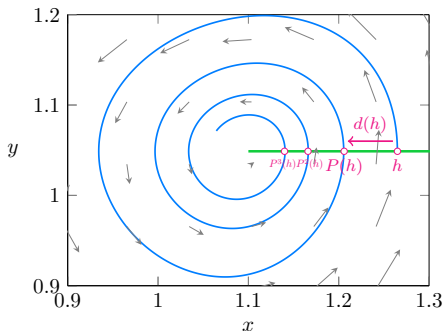


- Poincaré first return map $P(h)$
- Displacement $d(h) = P(h) - h$
- Limit cycle $\leftrightarrow$ isolated zero of d
- Abelian integral $\mathcal{I}(h)$:

$$\oint_{H^{-1}(h)} f(x, y) dy - g(x, y) dx$$

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- Poincaré first return map $P(h)$
- Displacement $d(h) = P(h) - h$
- Limit cycle $\Leftrightarrow$ isolated zero of d
- Abelian integral $\mathcal{I}(h)$:

$$\oint_{H^{-1}(h)} f(x, y) dy - g(x, y) dx$$

$$\begin{cases} \dot{x} = -\partial_y H(x, y) + \varepsilon f(x, y) \\ \dot{y} = \partial_x H(x, y) + \varepsilon g(x, y) \end{cases}$$

Poincaré-Pontryagin theorem

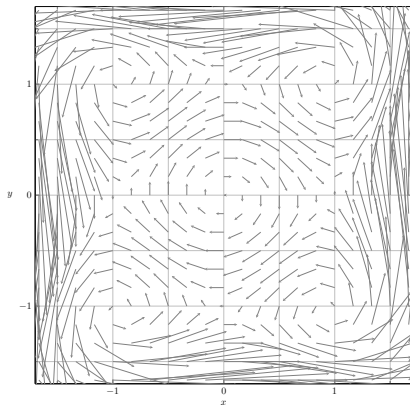
The Abelian integral $\mathcal{I}(h)$ approximates the displacement function $d(h)$ for small ε :

$$d(h) = \varepsilon(\mathcal{I}(h) + O(\varepsilon)) \quad \text{when } \varepsilon \rightarrow 0$$



- Hamiltonian system:

$$\begin{cases} \dot{x} = -4y(y^2 - 1.1) \\ \dot{y} = 4x(x^2 - 0.9) \end{cases}$$

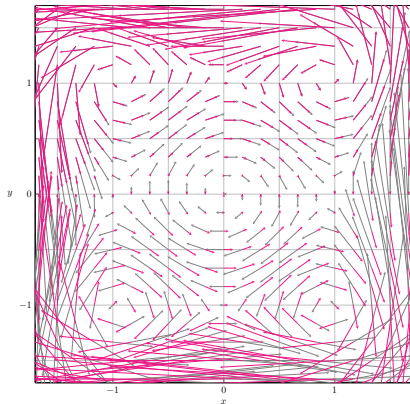


A Pseudo-Hamiltonian Quartic System



■ **pseudo**-Hamiltonian system:

$$\begin{cases} \dot{x} = -4yy(y^2 - 1.1) \\ \dot{y} = 4yx(x^2 - 0.9) \end{cases}$$



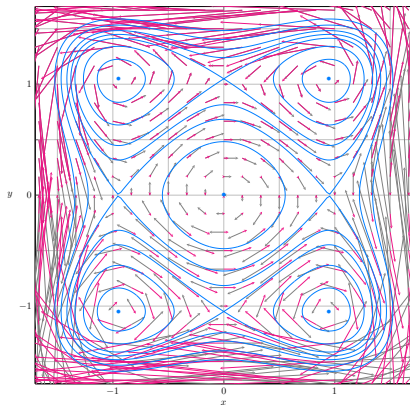
A Pseudo-Hamiltonian Quartic System



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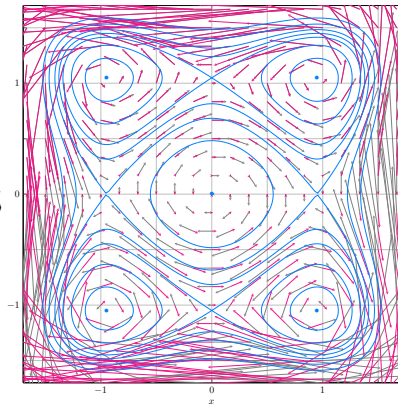


- **pseudo**-Hamiltonian system:

$$\begin{cases} \dot{x} = -4y(y^2 - 1.1) + \varepsilon f(x, y) \\ \dot{y} = 4x(x^2 - 0.9) + \varepsilon g(x, y) \end{cases}$$

- same geometric orbits after rescaling
- $\simeq$ perturbations without rescaling:

$$\frac{f(x, y)}{y}, \frac{g(x, y)}{y} \in \langle x^i y^j, i \geq 0, j \geq -1, i+j \leq 3 \rangle$$



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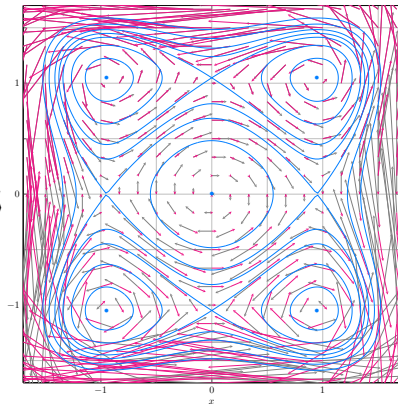
Generalized Poincaré-Pontryagin theorem

The *generalized* Abelian integral:

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approximates the displacement function $d(h)$ for small ε :

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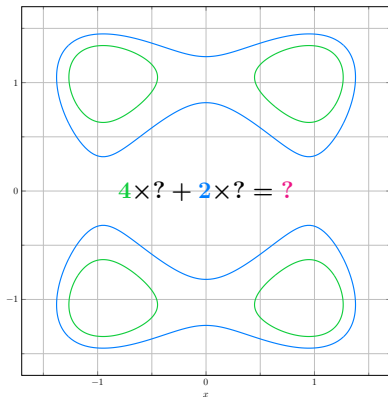
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$\Rightarrow$ The finiteness of $\mathcal{Z}(4)$ does not apply, but we still have some tools of the Hamiltonian case!



$$f(x, y) = \begin{matrix} 1 & x & y & x^2 & xy \\ y^2 & x^3 & x^2y & xy^2 & y^3 \\ x^4 & x^3y & x^2y^2 & xy^3 & y^4 \end{matrix}$$

$$g(x, y) = \begin{matrix} 1 & x & y & x^2 & xy \\ y^2 & x^3 & x^2y & xy^2 & y^3 \\ x^4 & x^3y & x^2y^2 & xy^3 & y^4 \end{matrix}$$



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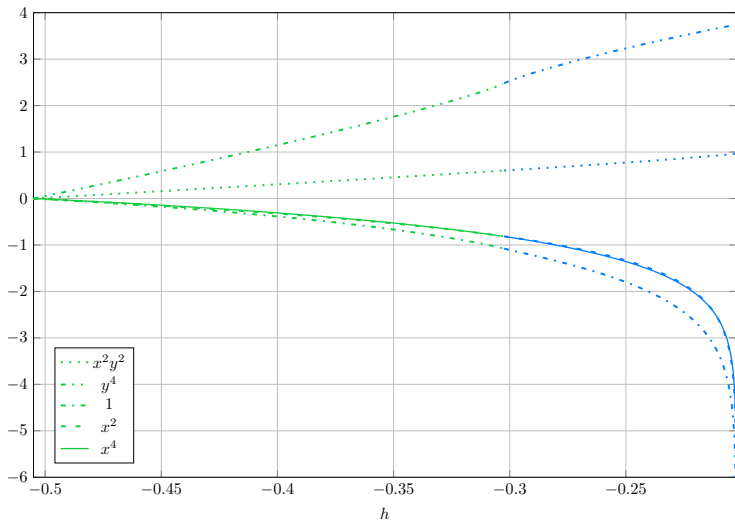
- symmetry requirements
- linear relations from Green's formula: $\partial_x \frac{f(x,y)}{y} \propto \partial_y \frac{g(x,y)}{y}$

$$\mathcal{I}(h) = \oint_{H^{-1}(h)} \frac{\alpha_{00} + \alpha_{20}x^2 + \alpha_{22}x^2y^2 + \alpha_{40}x^4 + \alpha_{04}y^4}{y} dx$$

Numerically Optimizing the Number of Zeros



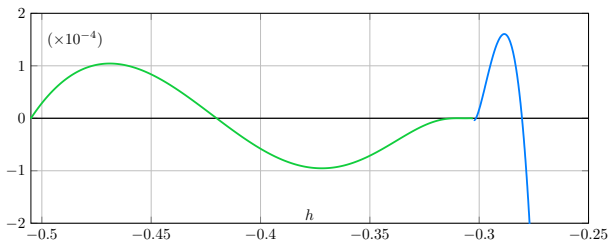
- Find coefficients of $\mathcal{I}(h) = \alpha_{00}\mathcal{I}_{00}(h) + \alpha_{20}\mathcal{I}_{20}(h) + \alpha_{22}\mathcal{I}_{22}(h) + \alpha_{40}\mathcal{I}_{40}(h) + \alpha_{04}\mathcal{I}_{04}(h)$.



Numerically Optimizing the Number of Zeros



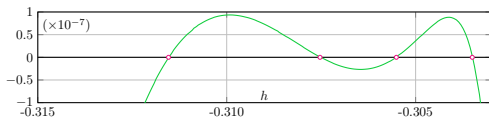
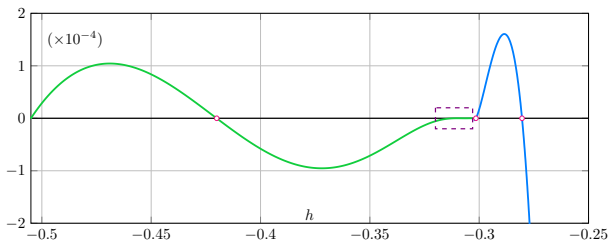
α_{00}	=	-0.78622148667854837664
α_{20}	=	0.87723523612653436051
α_{22}	=	1
α_{40}	=	0.23742713894293038223
α_{04}	=	-0.21823846173078863753



Numerically Optimizing the Number of Zeros



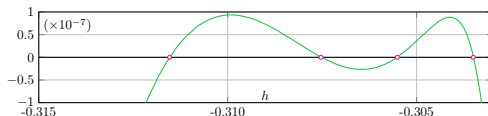
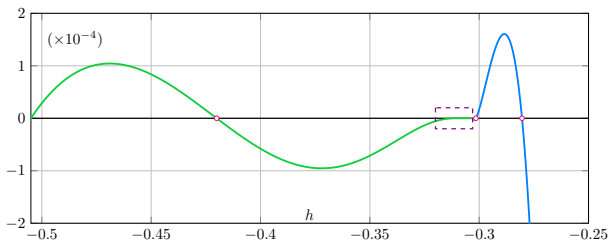
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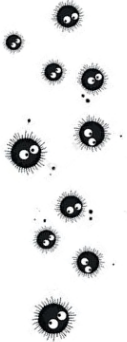


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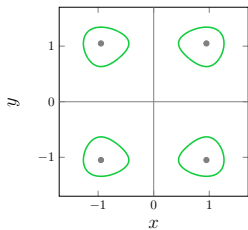
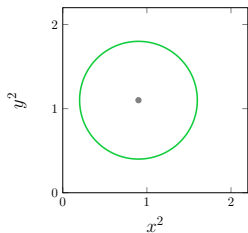
$$4 \times 5 + 2 \times 2 = 24$$

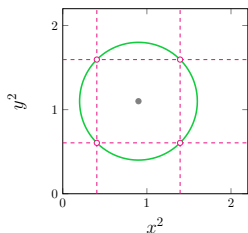
Outline

- 
- 1 A quartic example for Hilbert 16th problem
 - 2 Computing Abelian integrals with rigorous polynomial approximations
 - 3 Wronskian and extended Chebyshev systems
 - 4 Conclusion



$$0 < r (= \sqrt{h}) < 0.9$$





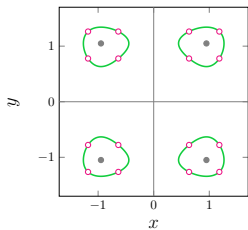
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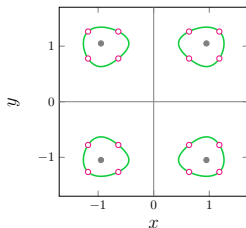
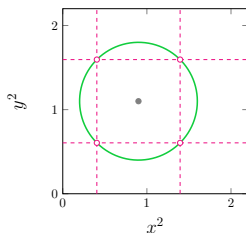
$$x_{\min} = 0.9 - \frac{r}{\sqrt{2}}$$

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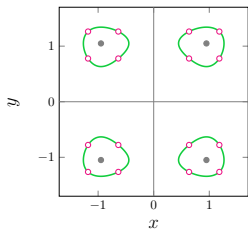
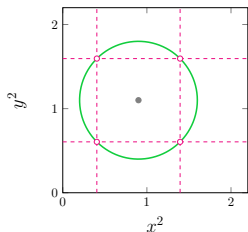




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$$\begin{aligned} y_{\text{up}}(x) &= \sqrt{1.1 + \sqrt{r^2 - (x^2 - 0.9)^2}} \\ y_{\text{down}}(x) &= \sqrt{1.1 - \sqrt{r^2 - (x^2 - 0.9)^2}} \\ x_{\text{left}}(y) &= \sqrt{0.9 - \sqrt{r^2 - (y^2 - 1.1)^2}} \\ x_{\text{right}}(y) &= \sqrt{0.9 + \sqrt{r^2 - (y^2 - 1.1)^2}} \end{aligned}$$



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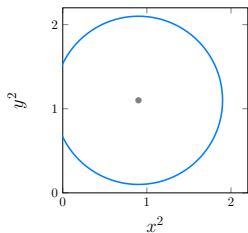
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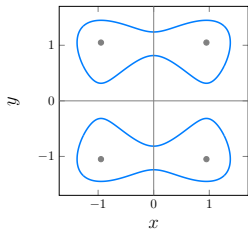
$$x_{\text{left}}(y) = \sqrt{0.9 - \sqrt{r^2 - (y^2 - 1.1)^2}}$$

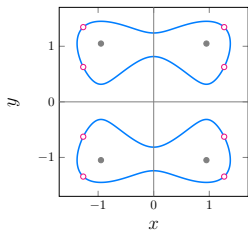
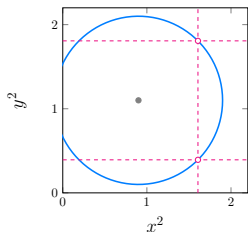
$$x_{\text{right}}(y) = \sqrt{0.9 + \sqrt{r^2 - (y^2 - 1.1)^2}}$$

$$\begin{aligned} \mathcal{I}(h) &= \oint_{H^{-1}(h)} \frac{g(x, y)}{y} dx = \int_{x_{\min}}^{x_{\max}} \left(\frac{g(x, y_{\text{up}}(x))}{y_{\text{up}}(x)} - \frac{g(x, y_{\text{down}}(x))}{y_{\text{down}}(x)} \right) \\ &+ \int_{y_{\min}}^{y_{\max}} \left(\frac{g(x_{\text{left}}(y), y)}{x_{\text{left}}(y)} + \frac{g(x_{\text{right}}(y), y)}{x_{\text{right}}(y)} \right) \frac{y^2 - 1.1}{\sqrt{r^2 - (y^2 - 1.1)^2}} dy. \end{aligned}$$



$$0.9 < r (= \sqrt{h}) < 1.1$$





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Definition

A pair $(P, \varepsilon) \in \mathbb{R}[X] \times \mathbb{R}_+$ is a rigorous polynomial approximation (RPA) of f for a given norm $\|\cdot\|$ if $\|f - P\| \leq \varepsilon$.

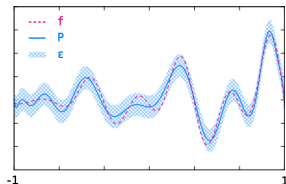


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Example: sup-norm over $[-1, 1]$:

$$f \in (P, \varepsilon) \Leftrightarrow |f(t) - P(t)| \leq \varepsilon \quad \forall t \in [-1, 1]$$





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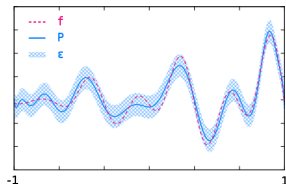
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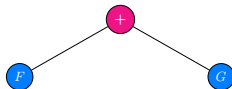
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$$\blacksquare (P, \varepsilon) + (Q, \eta) := (P + Q, \varepsilon + \eta),$$



Example:

$$r(t) = f(t) + g(t)$$





Definition

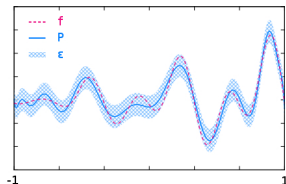
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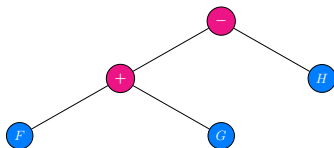
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Example:

$$r(t) = f(t) + g(t) - h(t)$$





Definition

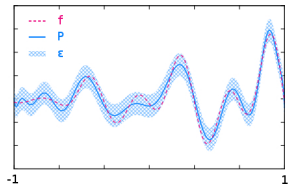
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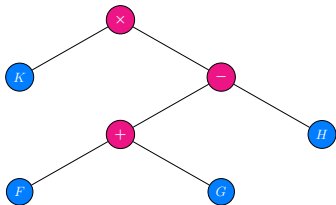
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Example:

$$r(t) = k(t)(f(t) + g(t) - h(t))$$





Definition

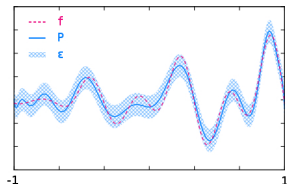
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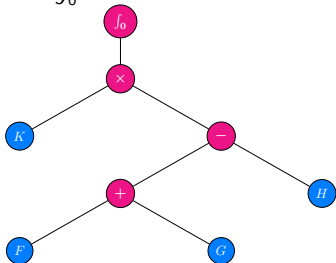
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Definition

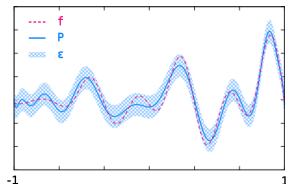
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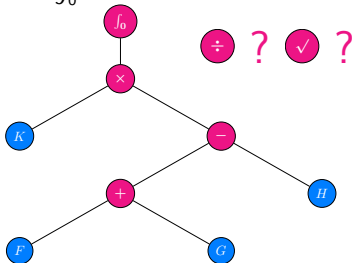
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Example:

$$r(t) = \int_0^t k(s)(f(s) + g(s) - h(s))ds$$





General scheme

- ▶ Fixed-point equation $\mathbf{T} \cdot \varphi = \varphi$ with $\mathbf{T}$ contracting,
- ▶ Approximation φ° to exact solution φ^* ,
- ▶ Compute *a posteriori* error bounds with Banach theorem.



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Banach Fixed-Point Theorem

If (X, d) is complete and $\mathbf{T}$ **contracting** of ratio $\lambda < 1$,

- ▶ $\mathbf{T}$ admits a unique fixed-point φ^* , and
- ▶ For all $\varphi^\circ \in X$,

$$\frac{d(\varphi^\circ, \mathbf{T} \cdot \varphi^\circ)}{1 + \lambda} \leq d(\varphi^\circ, \varphi^*) \leq \frac{d(\varphi^\circ, \mathbf{T} \cdot \varphi^\circ)}{1 - \lambda}.$$



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- ▶ Fixed-point equation $\mathbf{T} \cdot \varphi = \varphi$ with $\mathbf{T}$ contracting,
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If (X, d) is complete and $\mathbf{T}$ **contracting** of ratio $\lambda < 1$,

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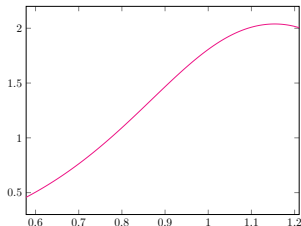
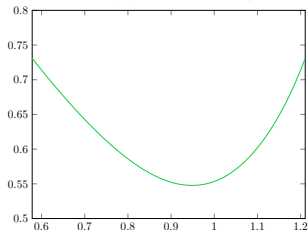
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- ▶ Applications to numerous function space problems.

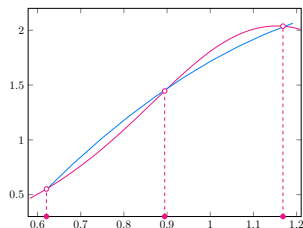
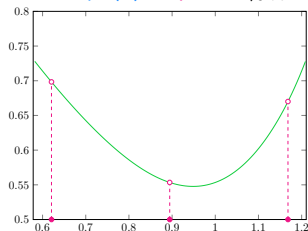


- Approximation $\varphi^\circ(x)$ of $\varphi^* = x^2/y_{\text{down}}(x)$ using Chebyshev interpolation:



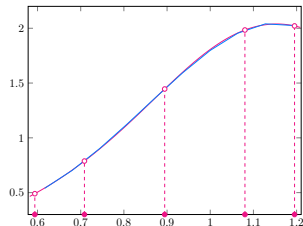
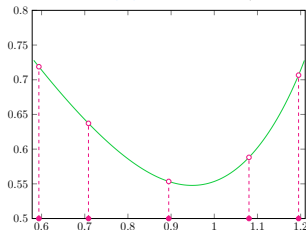


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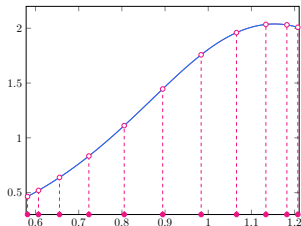
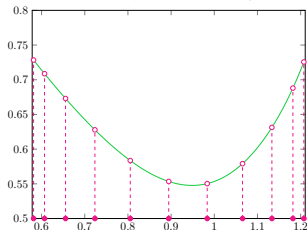


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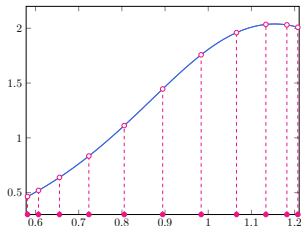
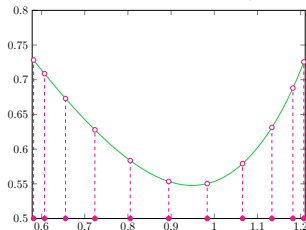


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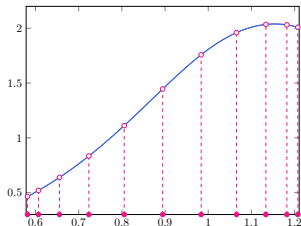
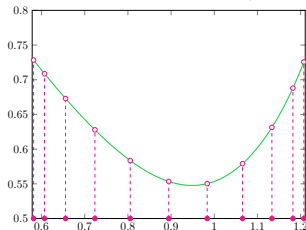


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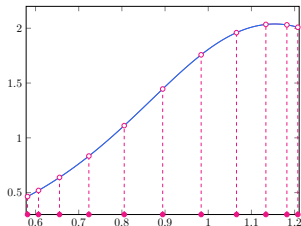
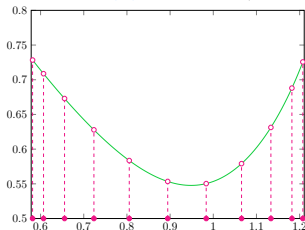
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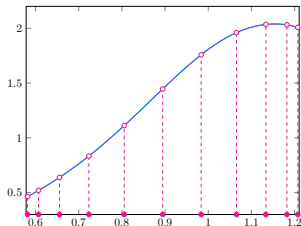
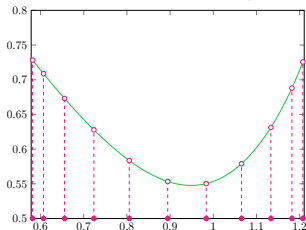
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- Apply the Banach fixed-point theorem:

$$\|\varphi^\circ - \mathbf{T} \cdot \varphi^\circ\| = \|\psi(y_{\text{down}}\varphi^\circ - x^2)\| \leq \eta$$



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Square Root of a RPA



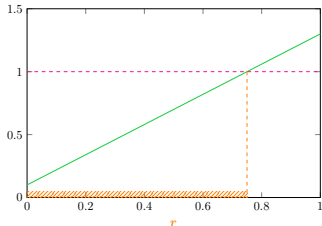
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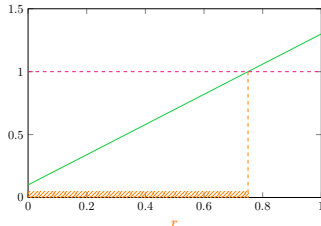
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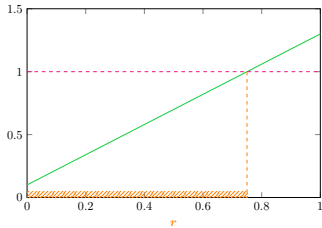
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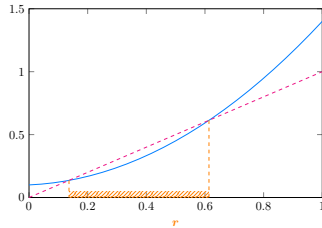
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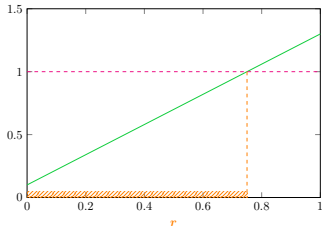
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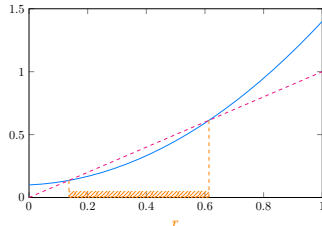
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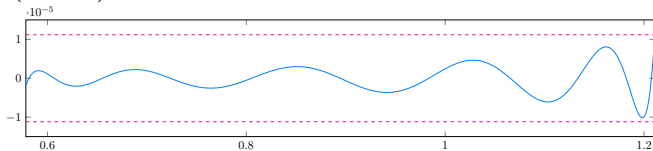
► Apply the Banach fixed-point theorem!

Rigorous Computation of an Abelian Integral

Using Degree $N = 10$



► $\sqrt{0.8 - (x^2 - 0.9)^2}$:

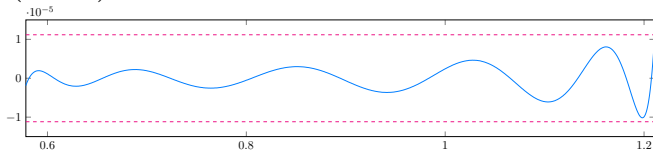


Rigorous Computation of an Abelian Integral

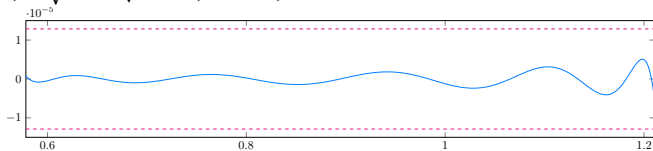
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► $\sqrt{0.8 - (x^2 - 0.9)^2}$:



► $y_{\text{down}}(x) = \sqrt{1.1 - \sqrt{0.8 - (x^2 - 0.9)^2}}$:

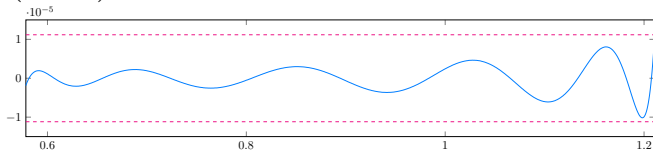


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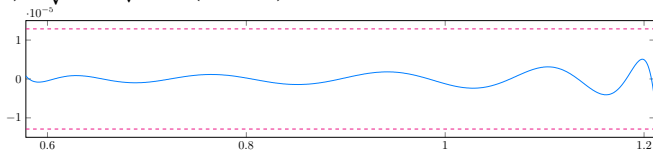
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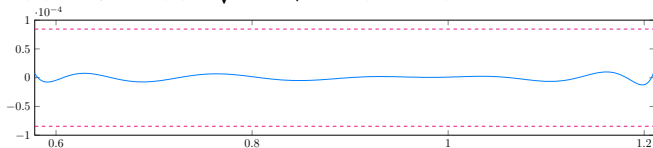
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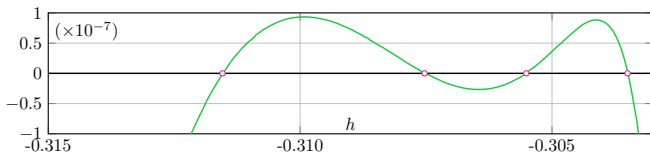
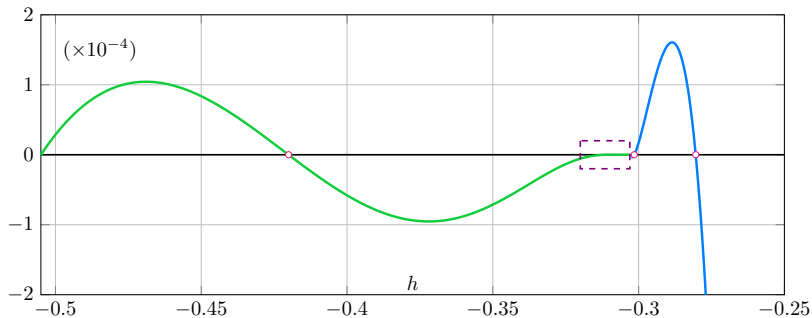
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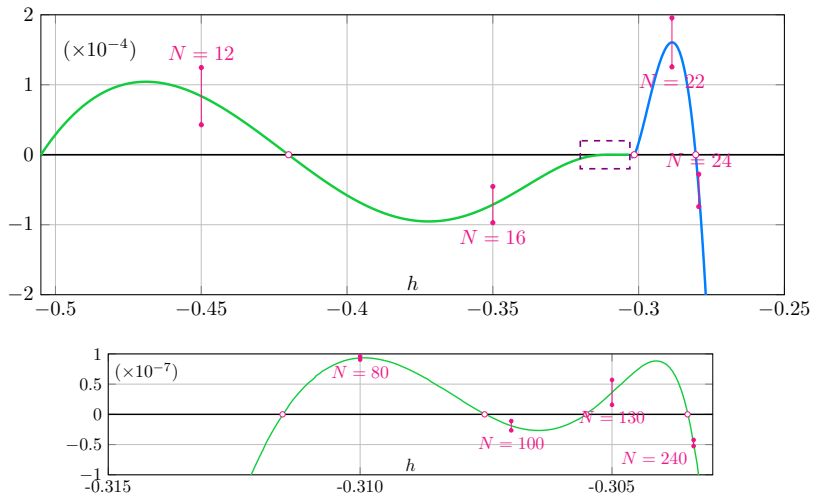
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Validation of Our Result



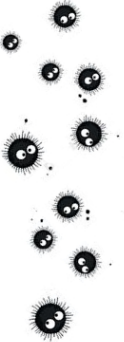
Validation of Our Result





$$4 \times 5 + 2 \times 2 = 24$$

Outline

- 
- 1 A quartic example for Hilbert 16th problem
 - 2 Computing Abelian integrals with rigorous polynomial approximations
 - 3 Wronskian and extended Chebyshev systems
 - 4 Conclusion



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- but no **rigorous** proof!



$$\oint_{H=h} \frac{f(x,y)dy - g(x,y)dx}{y} = \iint_{H \leq h} \left(\partial_x \frac{f(x,y)}{y} + \partial_y \frac{g(x,y)}{y} \right) dx dy$$



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- By creative telescoping, one finds a differential equation for $\mathcal{I}(h)$.

DiffEq[4, 0]

$$\begin{aligned} & \left(-128 h^5 x^0 y^2 + 336 h^4 x^0 y^4 - 288 h^3 x^0 y^6 + 80 h^2 x^0 y^8 - 64 h^5 y^0 y^2 + 480 h^4 x^0 y^2 y^2 - 800 h^3 x^0 y^4 y^2 + 464 h^2 x^0 y^6 y^2 - 80 h x^0 y^8 y^2 + \right. \\ & \quad \left. 144 h^4 y^0 y^4 - 544 h^3 x^0 y^4 y^4 + 576 h^2 x^0 y^4 y^6 - 176 h x^0 y^6 y^4 - 96 h^3 y^0 y^6 + 208 h^2 x^0 y^6 y^6 - 112 h x^0 y^8 y^6 + 16 h^2 y^0 y^8 - 16 h x^0 y^8 y^8 \right) D_h^4 + \\ & \left(-640 h^4 x^0 y^2 + 1632 h^3 x^0 y^4 - 1392 h^2 x^0 y^6 + 400 h x^0 y^8 - 320 h^4 y^0 y^2 + 1920 h^3 x^0 y^2 y^2 - 2848 h^2 x^0 y^4 y^2 + 1408 h x^0 y^6 y^2 - 160 x^0 y^8 y^2 + \right. \\ & \quad \left. 480 h^3 y^0 y^4 - 1520 h^2 x^0 y^4 y^4 + 1392 h x^0 y^4 y^6 - 352 x^0 y^6 y^4 - 192 h^2 y^0 y^6 + 416 h x^0 y^6 y^6 - 224 x^0 y^8 y^6 + 32 h y^0 y^8 - 32 x^0 y^8 y^8 \right) D_h^3 + \\ & \left(-480 h^3 x^0 y^2 + 1188 h^2 x^0 y^4 - 1020 h x^0 y^6 + 315 x^0 y^8 - 240 h^3 y^0 y^2 + 1080 h^2 x^0 y^2 y^2 - 1512 h x^0 y^4 y^2 + 660 x^0 y^6 y^2 + \right. \\ & \quad \left. 180 h^2 y^0 y^4 - 540 h x^0 y^4 y^4 + 378 x^0 y^4 y^6 - 48 h y^0 y^6 + 36 x^0 y^6 y^6 + 3 y^0 y^8 \right) D_h^2 \end{aligned}$$

$$(X_0 = 0.9, Y_0 = 1.1)$$



- Rigorous Polynomial Approximations at ordinary points¹

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- Rigorous Polynomial Approximations at ordinary points¹
- But **singularities!**

`DiffEq[0,0]:` order = 3, leading coefficient = $16 h (h - x\theta^2) (h - y\theta^2) (h - x\theta^2 - y\theta^2) (-x\theta^4 + 4 h y\theta^2 - 2 x\theta^2 y\theta^2 - y\theta^4)$

`DiffEq[2,0]:` order = 3, leading coefficient = $-16 h (h - x\theta^2) (h - y\theta^2) (h - x\theta^2 - y\theta^2) (2 h - x\theta^2 - y\theta^2)$

`DiffEq[4,0]:` order = 4, leading coefficient = $-16 h (h - x\theta^2) (h - y\theta^2) (h - x\theta^2 - y\theta^2) (8 h x\theta^2 - 5 x\theta^4 + 4 h y\theta^2 - 6 x\theta^2 y\theta^2 - y\theta^4)$

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- Analytic at $h = 0$

⇒ Initial conditions with **Laplace transform**

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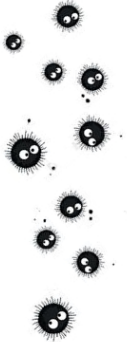
$\text{DiffEq}[2,2]: \text{order} = 4, \text{leading coefficient} = -16 h (h - X^2) (h - Y^2) (h - X^2 - Y^2) (4 h X^2 - 3 X^4 - 2 X^2 Y^2 + Y^4)$

$\text{DiffEq}[0,4]: \text{order} = 4, \text{leading coefficient} = 16 h (h - X^2) (h - Y^2) (h - X^2 - Y^2) (X^4 + 4 h Y^2 - 2 X^2 Y^2 - 3 Y^4)$

- Analytic at $h = 0$
 - ⇒ Initial conditions with **Laplace transform**
- log singularities at $h = X_0^2 \dots$
 - ⇒ Other rigorous approximation tools.

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Outline

- 
- 1 A quartic example for Hilbert 16th problem
 - 2 Computing Abelian integrals with rigorous polynomial approximations
 - 3 Wronskian and extended Chebyshev systems
 - 4 Conclusion



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- Exploring properties of the Wronskian using **symbolic-numeric** tools and Creative Telescoping.



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- **Future work:** Generalization to other systems?